

Comments on Academia-Industry Collaboration based on the Bosch Experience in the PR2 Beta Program

Jan Becker

Alan Robotics Alan Applications

Research and Technology Center North America



Bosch

Bosch Group

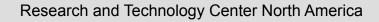
- Founded 1886, privately held (Robert Bosch Foundation and Bosch Family)
- → ~300.000 employees, ~47b Euro revenue (2010)
- Divisions: Automotive, Industrial Technology, Consumer Goods, Building Technologies, Solar Technologies
- Largest Automotive Supplier worldwide

Bosch Corporate Research

→ 1300 employees

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Offices in Germany, USA, Japan, China, Singapore, Russia





Bosch Research and Technology Center NA

- → Offices
 - Palo Alto, CA
 - Pittsburgh, PA
 - Cambridge, MA
- Topics

- HMI design, car infotainment, web technologies
- energy materials and technologies, complex simulations
- software engineering
- MEMS sensors, IC design, wireless solutions
- autonomous technologies/systems



Robotics



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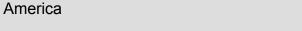


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PR2 Beta Program

- Participant in the Willow Garage's PR2 Beta Program
 - 10 top academic research institutes
 - Bosch is the only corporate participant
- Development and contribution to open source software
- Collaboration with Willow Garage and the PR2 community







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Making robots cheaper, more capable, and safer Bosch's contribution to the PR2 Beta Program

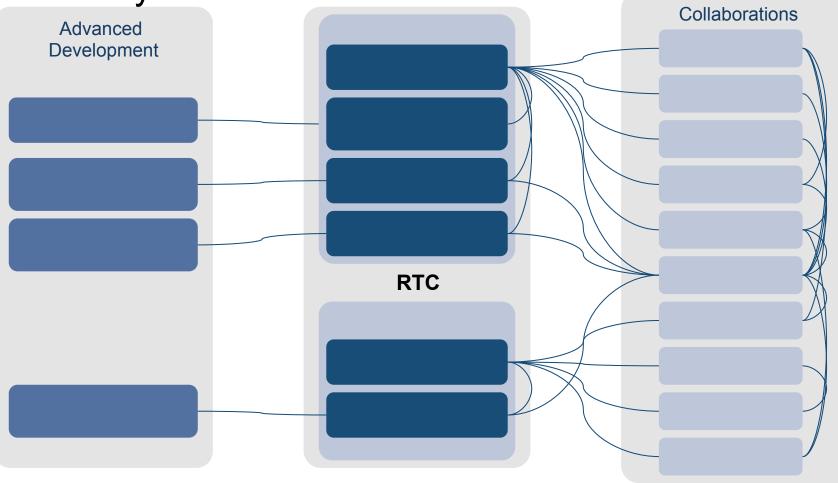
Alan R2 Developing the P Robotics Alan Robotics

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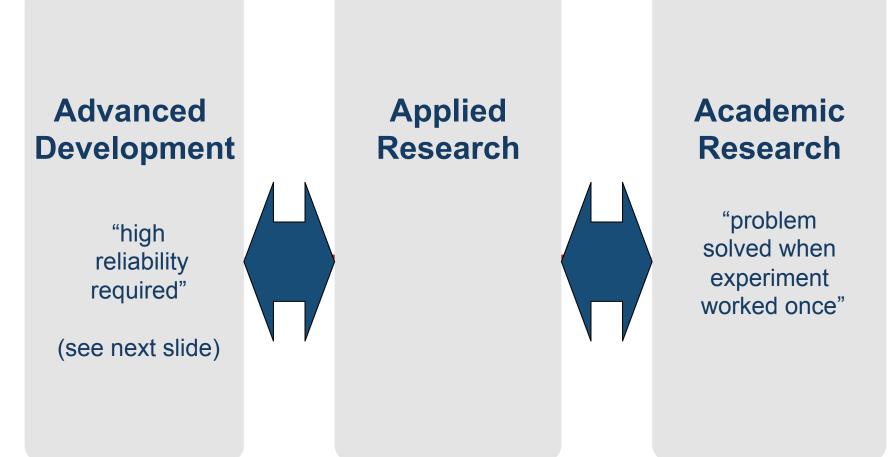
Industry Collaborations



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Academia-Industry Collaboration



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Safety Goals acc. ISO 26262

IEC EN 61500

Allowable dangerous failures per hour of operation

	I IE	C EN 61508	~ ~	ſ	
Safety Integrity Level	mittlere Wahrscheinlichkeit eines gefahrbringenden Ausfalls bei Anforderung der Sicherheitsfunktion	Rate gefahrbringender Ausfälle der Sicherheitsfunktion [Fehler/h]	IEC EN 61508	ISO CD 26262	
	PFD	PFH	SIL	ASIL	
	-	-	QM	QM	
	>= 10 ⁻² bis < 10 ⁻¹	>= 10 ⁻⁶ bis < 10 ⁻⁵ < 10.000 FIT	1	А	
	$>= 10^{-3}$ bis $< 10^{-2}$	$>= 10^7$ bis $< 10^6$	2	В	
		< 1.000 FIT		С	
	>= 10 ⁻⁴ bis < 10 ⁻³	$>= 10^8$ bis $< 10^7$	3	0	
		< 100 FIT		D	
	>= 10 ⁻⁵ bis < 10 ⁻⁴	>= 10 ^{.9} bis < 10 ^{.8}	4	-	
	>= 10 bis < 10	< 10 FIT	4		
	http://www.uwe-lindenberg.de		1 FIT	= 1 Fehler / 10 ⁹ h	
		continuous system	-		
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How to bridge the gap?

- Industrial Requirements
 - Quality
 - Reliability
 - Reusability
- Academia

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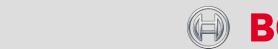
- Current success measures for Academia
 - Productivity: total number of papers
 - Impact: citations of papers



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How to bridge the gap?

- → ROS / PR2 Beta Program Approach
 - Academia and industry in one program
 - Common basis is open source repository
 - Requirement to open source commitments
 - Request to open source code related to publications
 - Establishing standard for academia
 - Quantitative software metrics
- → Results
 - Increased exchange of code
 - Interaction between sites
 - Repeatability of results
 - Reusability of algorithms through standardization



How to bridge the gap?

- What can be improved?
 - Quality
 - Reliability
- Additional Incentives
 - Qualitative software metrics

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Summary

- Industry-academia collaboration
 - Potential gap in objectives
- Academic incentive is number of papers
 - Results may not repeatable, algorithms not reproducible
- Academia-industry-collaboration based on open source collaboration
 - Can help bridge the gap

http://www.boschresearch.com http://www.ros.org/wiki/bosch-ros-pkg http://bosch-ros-pkg.sourceforge.net

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