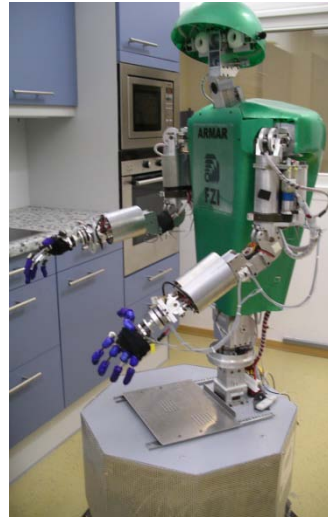




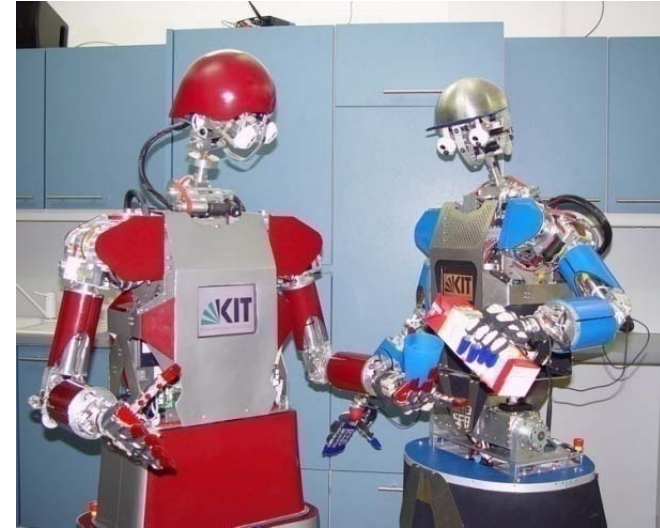
ARMAR, 2000



ARMAR-II, 2002



ARMAR-IIIa, 2006



ARMAR-IIIb, 2008

- Collaborative Research Center 588: Humanoid Robots - Learning and Cooperating Multimodal Robots (SFB 588)
  - Funded by the German Research Foundation (DFG: Deutsche Forschungsgemeinschaft )

- Programming by Demonstration
  - Grasp Planning
  - Motion Planning
  - Observation of Humans
  - Multimodal Human-Robot-Interaction
  - Object Recognition and Localization
- 
- Main Robotic Projects
    - DESIRE (BMBF)
    - DEXMART (EU)
    - GRASP (EU)
    - SFB588 (DFG)

